

# Graph Neural Networks in Biology: Introduction

Alexander Schönhuth  
Luna Pianesi



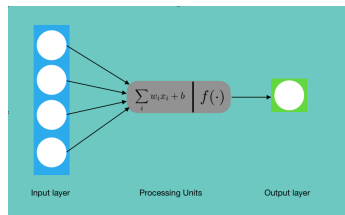
Bielefeld University  
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# *Graph Neural Networks: Motivation*

# *Neural Networks*

# NEURONS

## LINEAR + ACTIVATION FUNCTION



$$\text{output} = a(w^T \cdot x + b)$$

*Note: replace  $f$  in Figure by  $a$ !*

**Neuron: linear function followed  
by activation function**

## Examples

- Linear regression:

$$a = \text{Id}$$

$a$  is identity function

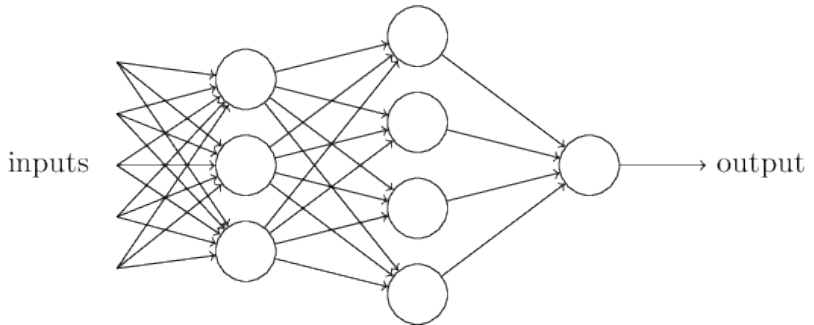
- Perceptron:

$$a(x) = \begin{cases} 1 & x \geq 0 \\ 0 & x < 0 \end{cases}$$

$a$  is step function

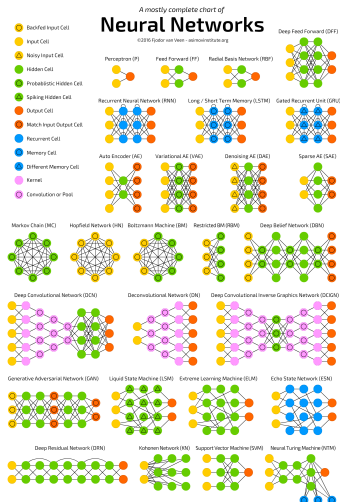
# NEURAL NETWORKS

## CONCATENATING NEURONS



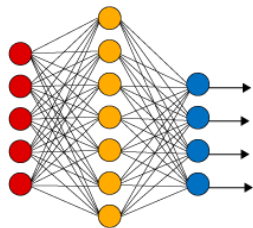
# NEURAL NETWORKS

## ARCHITECTURES (CHART FROM 2016)

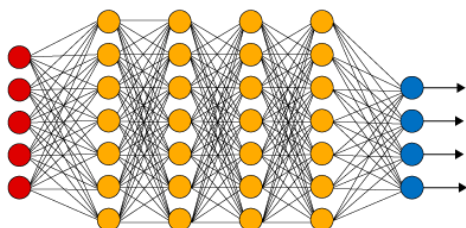


# DEEP NEURAL NETWORKS

Simple Neural Network



Deep Learning Neural Network



● Input Layer

● Hidden Layer

● Output Layer

*Width* = Number of nodes in a hidden layer

*Depth* = Number of hidden layers

*Deep* =  $\text{depth} \geq 8$  (for historical reasons)

# NEURAL NETWORKS

## FORMAL DEFINITION

- ▶ Let  $\mathbf{x}^l \in \mathbb{R}^{d(l)}$  be all outputs from neurons in layer  $l$ , where  $d(l)$  is the *width* of layer  $l$ .
- ▶ Let  $y \in V$  be the output.
- ▶ Let  $\mathbf{x} =: \mathbf{x}^0$  be the input.
- ▶ Then

$$\mathbf{x}^l = \mathbf{a}^l(\mathbf{W}^{(l)}\mathbf{x}^{l-1} + \mathbf{b}^l)$$

where  $\mathbf{a}^l(\cdot) = (a_1^l(\cdot), \dots, a_{d(l)}^l(\cdot))$ ,  $\mathbf{W}^{(l)} \in \mathbb{R}^{d(l) \times d(l-1)}$ ,  $\mathbf{b}^l \in \mathbb{R}^{d(l)}$

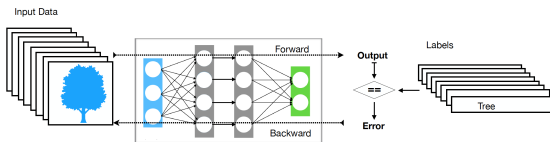
- ▶ The function  $f$  representing a neural network with  $L$  layers (with depth  $L$ ) can be written

$$y = f(\mathbf{x}^0) = f^{(L)}(f^{(L-1)}(\dots(f^{(1)}(\mathbf{x}^{(0)}))\dots))$$

where  $\mathbf{x}^l = f^{(l)}(\mathbf{x}^{l-1}) = \mathbf{a}^l(\mathbf{W}^{(l)}\mathbf{x}^{l-1} + \mathbf{b}^l)$



# TRAINING: BACKPROPAGATION



- E.g. let  $X$  be a set of images, labels 1 and 0: tree or not

- Let

$$f_{(\mathbf{w}, \mathbf{b})} : X \rightarrow \{0, 1\} \quad \text{and} \quad \hat{f} : X \rightarrow \{0, 1\}$$

be the network function ( $f_{\mathbf{w}, \mathbf{b}}$ ) and the true function ( $\hat{f}$ )

- $L(f_{(\mathbf{w}, \mathbf{b})}, \hat{f})$  loss function, differentiable in network parameters  $\mathbf{w}, \mathbf{b}$
- *Back Propagation*: Minimize  $L(f, \hat{f})$  through gradient descent
  - ☞ Heavily parallelizable!
- **Decisive**: Ratio number of parameters and training data

# *Why Neural Networks?*

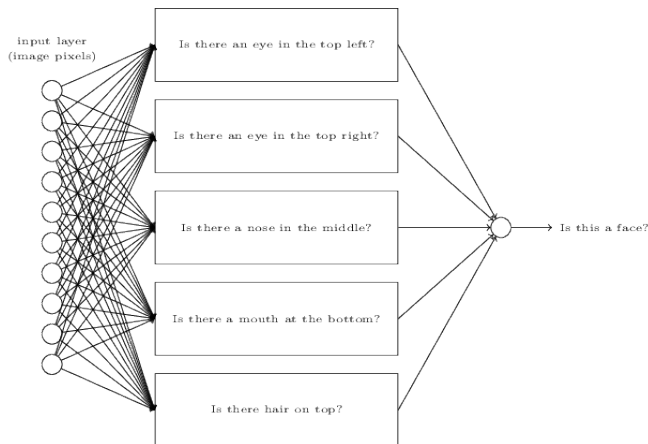
# WHY NEURAL NETWORKS?

Given an (unknown) functional relationship  $f : \mathbb{R}^d \rightarrow V$ , why should we learn  $f$  by approximating it with a neural network?

## *Practical, Intuitive Consideration*

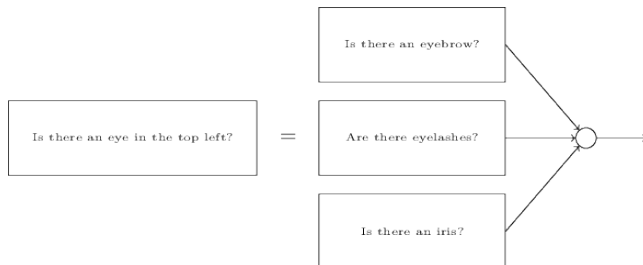
# DEEP LEARNING

## INTUITIVE EXPLANATION



► *Face recognition: decompose classification task into subtasks*

# DEEP LEARNING IS INTUITIVE



- ▶ *Face recognition*: decompose subtask (eye recognition) into sub-subtasks
- ▶ Subtasks are composed into overall task “layer by layer”

# RUNNING EXAMPLE: MNIST CLASSIFICATION

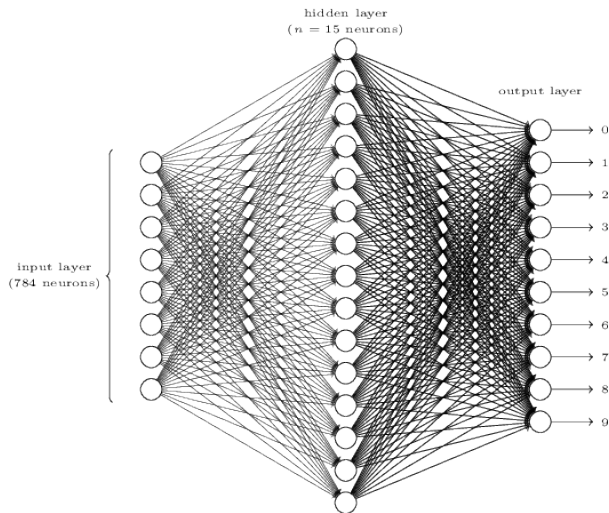
DATA, FUNCTION



$$f : \mathbb{R}^{28 \times 28 = 784} \longrightarrow \{0, 1, \dots, 9\} \quad (1)$$

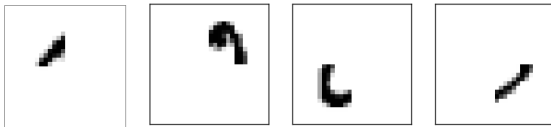
# RUNNING EXAMPLE

MODEL CLASS: NN WITH 1 HIDDEN LAYER





# RUNNING EXAMPLE



together makes



*Neurons of hidden layer recognize characterizing parts of digit*

## *Theoretical Consideration*

# THE UNIVERSAL APPROXIMATION THEOREM

First version formulated by George Cybenko in 1989.

## Theorem

*A feedforward network with a single hidden layer containing a finite number of neurons can approximate any nonconstant, bounded and continuous function with arbitrary closeness, as long as there are enough hidden nodes.*

# *Why Deep Learning?*

# RULE OF THUMB

*One needs approximately*

*as many training data  
as there are parameters*

*in the class of models*

# MORE LAYERS

## MOTIVATION

- We save on neurons/parameters, while increasing number of steps, by increasing depth!

If you are curious about a working example: watch Lecture 02 by Prof. Schönhuth here <https://gds.techfak.uni-bielefeld.de/teaching/2022winter/bioadl>

# WHY DEEP LEARNING

- ▶ We need only  $O(n + 1)$  (and not  $O(2n)$ ) parameters to model a constellation with  $2n$  steps and one symmetry axis
- ▶ Hence, we only need  $O(n + 1)$  training data, and not  $O(2n)$  (like SVM or Nearest Neighbour)
- ▶ In general  $O(n^l)$  (symmetric) steps need only  $O(nl)$  training data
- ▶ This illustrates why deeper NNs can deal with symmetry invariance in images

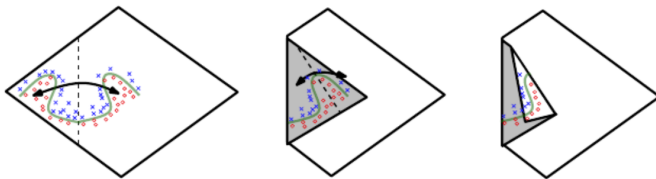
# WHY DEEP LEARNING

## Theorem (Universal Approximation; Montufar (2014))

*Let  $f$  be an NN with  $d$  inputs,  $l$  hidden layers (depth  $l$ ) of width  $n$  each. Then the number of differently labeled regions is*

$$O\left(\binom{n}{d}^{d(l-1)} n^d\right) \quad (2)$$

That is, the number of regions that can receive different labels is exponential in the depth (the number of hidden layers)  $l$ .





# DEEP LEARNING

## ASSUMPTIONS

- ▶ Model classes make certain assumptions about properties of the functions they aim to approximate
- ▶ Many model classes (such as Nearest Neighbors and SVM's) require *local consistency* and *smoothness*: nearby points are likely to receive the same label
- ▶ Deep neural networks make further assumptions such as invariance to shifts, rotations and mirroring

# IMAGENET AND ILSVRC

## DATASET AND FIRST RESULTS

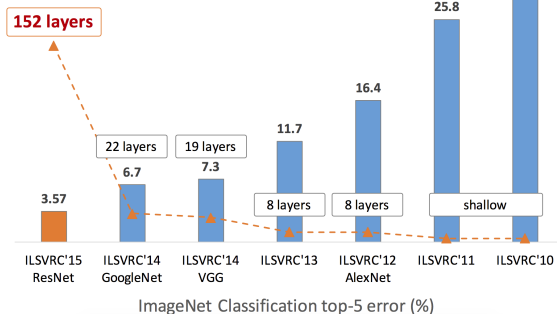


ImageNet examples: “beading plane”, “brown root rot fungus”, “scalded milk”,  
“common roundworm”

- ▶ *ImageNet dataset*: 16 million full color images; 20 000 categories
- ▶ *Starting point*: Le, Ranzato, Monga, Devin, Chen, Corrado, Dean & Ng: “Building high-level features using large scale unsupervised learning”, 2012, <https://ai.google/research/pubs/pub38115> achieved 15.3 % test accuracy
- ▶ *ILSVRC*: Image-Net Large-Scale Visual Recognition Challenge
  - ▶ 2012: 1000 categories; Training 1.2 million images; Validation 50 000 images; Test 150 000 images

# GOING DEEPER

## ImageNet experiments

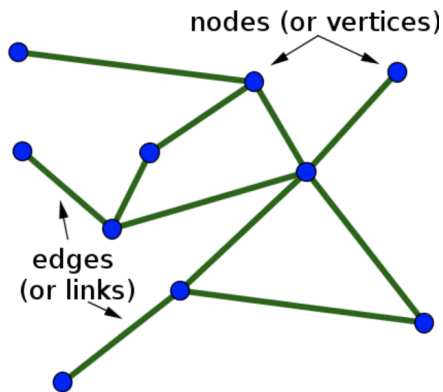


[https://icml.cc/2016/tutorials/icml2016\\_tutorial\\_deep\\_residual\\_networks\\_kaiminghe.pdf](https://icml.cc/2016/tutorials/icml2016_tutorial_deep_residual_networks_kaiminghe.pdf); Note: correct error rate for AlexNet is 15.4%

# *Graph Neural Networks: Introduction*

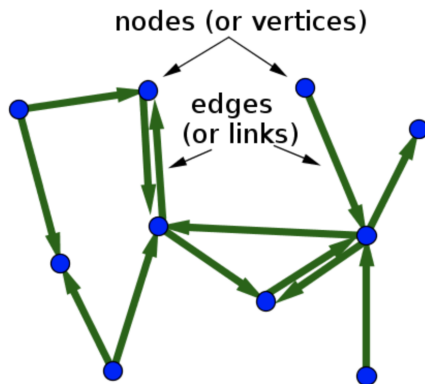
# *Graphs*

# GRAPHS: INTRODUCTION



From [https://mathinsight.org/network\\_introduction](https://mathinsight.org/network_introduction)

# DIRECTED GRAPH



From [https://mathinsight.org/network\\_introduction](https://mathinsight.org/network_introduction)

# GRAPHS, ADJACENCY MATRIX: DEFINITION

## DEFINITION [GRAPH]:

A graph  $G = (V, E)$  has vertices  $V$  and edges  $E \subset V \times V$ . If  $G$  is *directed*, the order  $(i, j) := (v_i, v_j) \in E$  matters (and edges are often referred to as *arcs*). If  $G$  is undirected,  $(i, j)$  can be considered unordered, so  $(i, j) = (j, i)$ .

## DEFINITION [ADJACENCY MATRIX]:

Let  $G = (V, E)$  be a graph with vertices  $V$  and (directed) edges  $E$ . The *adjacency matrix*  $A = (a_{ij})_{1 \leq i, j \leq |V|}$  is defined by

$$a_{ij} = \begin{cases} 1 & \text{if } (i, j) \in E \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

*Remark:* If  $G$  is undirected,  $a_{ij} = 1$  implies  $a_{ji} = 1$ . Hence  $A$  is symmetric.

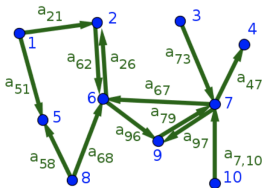


# ADJACENCY MATRIX: EXAMPLE

DEFINITION [ADJACENCY MATRIX]:

Let  $G = (V, E)$  be a graph with vertices  $V$  and (directed) edges  $E$ . The *adjacency matrix*  $A = (a_{ij})_{1 \leq i, j \leq |V|}$  is defined by

$$a_{ij} = \begin{cases} 1 & \text{if } (i, j) \in E \\ 0 & \text{otherwise} \end{cases} \quad (4)$$



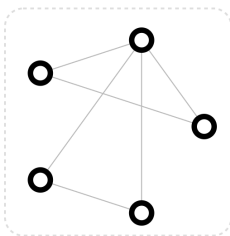
$$A = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

From [https://mathinsight.org/network\\_introduction](https://mathinsight.org/network_introduction)

## *Graphs: Storing Information*

# GRAPHS: STORING INFORMATION I

Graphs can store information in various ways



**V** Vertex (or node) attributes  
e.g., node identity, number of neighbors

**E** Edge (or link) attributes and directions  
e.g., edge identity, edge weight

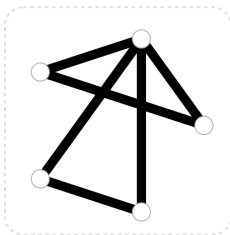
**U** Global (or master node) attributes  
e.g., number of nodes, longest path

Vertex attributes

From <https://distill.pub/2021/gnn-intro/>

# GRAPHS: STORING INFORMATION II

Graphs can store information in various ways



**V** Vertex (or node) attributes

e.g., node identity, number of neighbors

**E** Edge (or link) attributes and directions

e.g., edge identity, edge weight

**U** Global (or master node) attributes

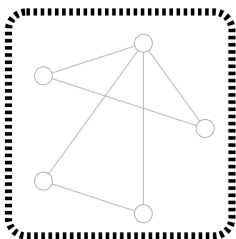
e.g., number of nodes, longest path

Edge attributes

From <https://distill.pub/2021/gnn-intro/>

# GRAPHS: STORING INFORMATION III

Graphs can store information in various ways



**V** Vertex (or node) attributes

e.g., node identity, number of neighbors

**E** Edge (or link) attributes and directions

e.g., edge identity, edge weight

**U** Global (or master node) attributes

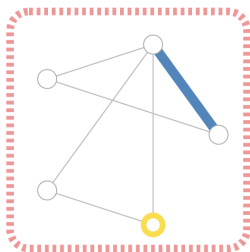
e.g., number of nodes, longest path

Global attributes

From <https://distill.pub/2021/gnn-intro/>

# GRAPHS: STORING INFORMATION IV

Graphs can store information in various ways



Vertex (or node) embedding



Edge (or link) attributes and embedding



Global (or master node) embedding

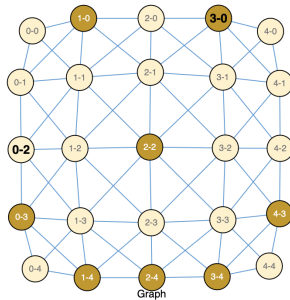
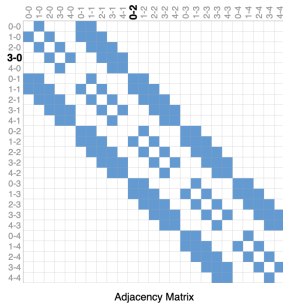


Embeddings: vector-valued information

From <https://distill.pub/2021/gnn-intro/>

## *Graphs: Examples*

# GRAPHS: IMAGES

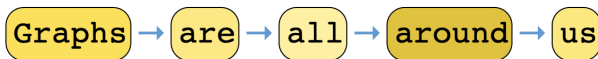


Graph and adjacency matrix of an image

From <https://distill.pub/2021/gnn-intro/>



# GRAPHS: TEXTS

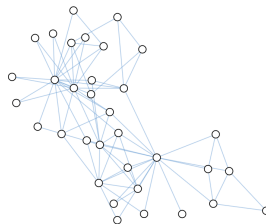
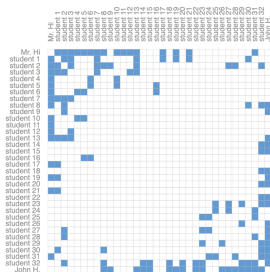


	Graphs	are	all	around	us
Graphs		■			
are			■		
all				■	
around					■
us					

Graph and adjacency matrix of a piece of text

From <https://distill.pub/2021/gnn-intro/>

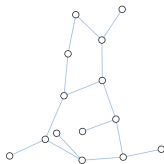
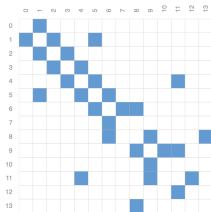
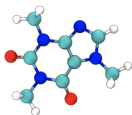
# GRAPHS: SOCIAL NETWORKS



Graph and adjacency matrix displaying interactions in karate club

From <https://distill.pub/2021/gnn-intro/>

# GRAPHS: MOLECULES

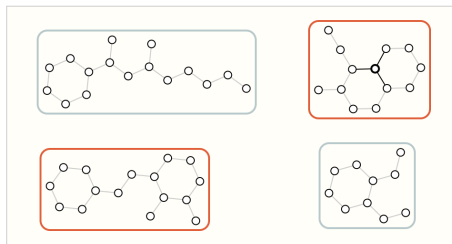


Graph and adjacency matrix of a molecule

From <https://distill.pub/2021/gnn-intro/>

## *Graphs: Learning Tasks*

# GRAPH LEVEL TASKS

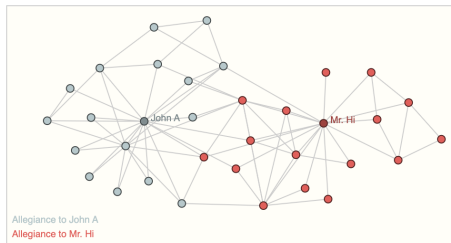


Structures in molecule graphs. Two rings (red) or not (black).

From <https://distill.pub/2021/gnn-intro/>

- Labels reflect statements about the entire graph.
- If unknown, determine using machine learning.

# NODE LEVEL TASKS

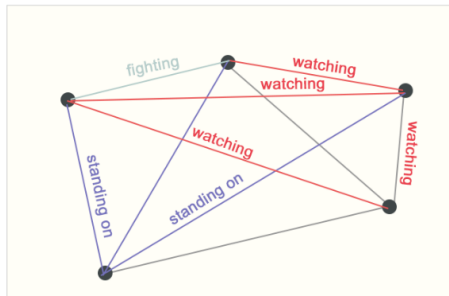


Karate club: Allegiance to either Mr. Hi (red) or John A. (gray)

From <https://distill.pub/2021/gnn-intro/>

- ▶ Labels reflect statements about individual nodes.
- ▶ Some may be known. Others not: determine using ML.

# EDGE LEVEL TASKS



Fight scene in image: elements (two fighters, arbiter, audience, mat).

Labels: relationships.

From <https://distill.pub/2021/gnn-intro/>

- Labels reflect statements about edges, so indicate relationships.
- Some relationships known. If not known: determine using ML.

# *Graphs: Machine Learning Challenges*



# NEURAL NETWORKS AND GRAPHS

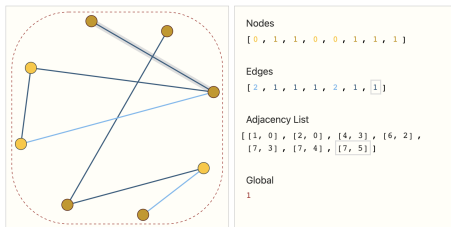
- ▶ Techniques for certain graphs available:
  - ▶ *Images = Grids*: Convolutional neural networks
  - ▶ *Text = Sequences*: Recurrent neural networks, attention networks
- ▶ Techniques for arbitrary graphs desirable:
  - ▶ *Social networks*: vary (heavily) by application
  - ▶ *Molecules*: plenty of different structures
  - ▶ *Other applications*: manifold interaction networks
- ▶ *Motivation*: Extend existing techniques to general graphs
- ▶ *Issue*: Get rid of regularity as a necessary condition

# GENERAL GRAPHS: INPUT

- ▶ Neural networks usually expect well-arranged input:
  - ▶ Rectangular, grid-like input
  - ▶ Sequence type input
  - ▶ Arrangement in terms of graph-type evaluation obvious
- ▶ Graphs may harbor four types of information:
  - ▶ Node information
  - ▶ Edge information
  - ▶ Global information
  - ▶ Connectivity

How to exploit them by appropriately arranging input?

# CHALLENGE: REPRESENTING INPUT



Suitable way of storing graph information. Colors: different information.

From <https://distill.pub/2021/gnn-intro/>

- ▶ Nodes: node information
- ▶ Edges: edge information
- ▶ Global: global information
- ▶ Adjacency List: connectivity information

# CHALLENGE: PERMUTATION INVARIANCE



From <https://distill.pub/2021/gnn-intro/>

- ▶ Graphs are permutation invariant
- ▶ *Goal:* Exploit data in permutation invariant way

*Thanks for your attention!*