Mining Data Streams II

Alexander Schönhuth



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TODAY

Mining Data Streams II: Overview

- Counting Ones in a Window:
 Totar-Gionis-Indyk-Motwani algorithm
- Decaying Windows

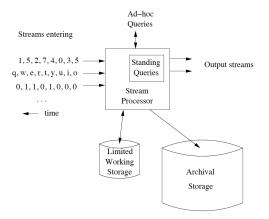
Learning Goals: Understand these topics and get familiarized



Counting Ones in a Window The Datar-Gionis-Indyk-Motwani Algorithm



DATA STREAM MANAGEMENT SYSTEM



A data stream management system

Adopted from mmds.org



DATA STREAM QUERIES

Issues

- Streams deliver elements rapidly: need to act quickly
- ▶ Thus, data to work on should fit in main memory
- New techniques required:
- Compute approximate, not exact answers
- 🖙 Hashing is a useful technique



COUNTING ONES IN WINDOW: PROBLEM

• Let $x_i \in \{0, 1\}$, earliest = leftmost = x_1 (unlike before)

$$x_1, \dots, x_t, \underbrace{x_{t+1}, \dots, x_{t+N-k+1}, \dots, x_{t+N}}_{\text{window of length } N}$$
(1)

► Situation:

- ▶ We have a window of length *N* on a binary stream
- Query: "how many ones are there in the last $k \leq N$ bits?"
- We cannot afford to store entire window
- Approximate algorithms required
- Present solution for binary streams first
- Thereafter extension for summing numbers



The Cost of Exact Counts

- ► One needs to store *N* bits to answer count-one-queries for arbitrary *k* ≤ *N*:
 - Assume one could use less than *N* bits
 - We need 2^N different representations to represent all possible 2^N bit strings of length N
 - Since we use less than *N* bits, there are two different bit strings $w \neq x$, for which we use the same representation

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- ▶ Let *k* be the first bit from the right where *w* and *x* disagree
- ► Example:
 - For w = 0101, x = 1010, we have k = 1
 - ▶ For *w* = 1001, *x* = 0101, we have *k* = 3



The Cost of Exact Counts

- ► One needs to store *N* bits to answer count-one-queries for arbitrary *k* ≤ *N*:
 - Let *k* be the first bit from the right where *w* and *x* disagree
 - ► Example:
 - For w = 0101, x = 1010, we have k = 1
 - For w = 1001, x = 0101, we have k = 3
 - ▶ So the counts of ones in the window of length *k* for *w* and *x* differ
 - But because we use identical representations for *w* and *x*, we will output the same count
 - This proves that one needs the full N bits to represent bit strings for exact count-one-queries.



► Situation:

- We consider a binary stream: elements are *bits*
- Let each element of the stream have a *timestamp*
- The first, *leftmost* element has timestamp 1, the second leftmost has timestamp 2, and so on; *i* is timestamp for x_i

$$\underbrace{x_1, \dots, x_t, x_{t+1}, \dots, x_M}_{\text{timestamps: } 1, \dots, t, t+1, \dots, M}$$
(2)

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 Goal: We like to count the ones among the N most recent (rightmost) elements/bits



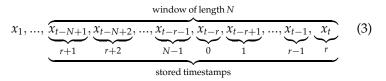
► *Goal:* We like to count the ones among the *N* most recent (rightmost) elements/bits

► Space requirements:

Storing timestamps modulo N, and

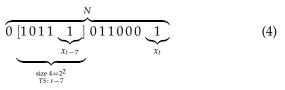
- marking rightmost timestamp as most recent
- allows to store positions of individual bits using $\log_2 N$ bits

• Illustration: Let t = mN + r.





- ► *Algorithm*: Divide window into *buckets*, contiguous bit substrings
- ► Bucket Representation: Store
 - The timestamp (TS) of its right end (figure: t 7), and
 - ► The *size* of the bucket, as the number of 1's in the bucket
 - ► The size is supposed to be a power of 2 (figure: 2²)

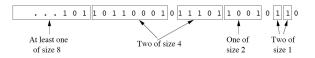


- ► Bucket Space Requirements:
 - ► Storing buckets: (TS, size)
 - TS between 0 and N 1, so requires $\log_2 N$ bits
 - ► Size: Storing $\log_2 j$, $0 \le j \le \log_2 N$ amount to $\log_2 \log_2 N$ bits
 - ► Requires *O*(log *N*) bits overall



DATAR-GIONIS-INDYK-MOTWANI BUCKET RULES

. . 1 0 1 1 0 1 1 0 0 0 1 0 1 1 1 0 1 1 0 0 1 0 1 1 0



Bit stream divided into buckets following DGIM rules

From mmds.org

- Buckets do not overlap; right end always is a 1
- ► Every 1, but not necessarily every 0 of window in some bucket
- Either one or two buckets for each possible size
- ► Size cannot decrease on earlier timestamps (moving to the left)



Key Ideas / Considerations

- ► Number of buckets representing a window must be small
- Estimate number of 1's in last k bits by exploiting known (because stored) bucket structure
- ► For any *k*, estimate has error of no more than 50%
- How to re-establish DGIM Bucket Rules quickly, on new bits arriving?

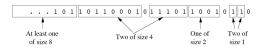


Storage Requirements Overall

- Each bucket represented using $O(\log N)$ bits (see before)
- Let 2^j be size of largest bucket: $2^j < N$ implies $j \le \log_2 N$
- So there are at most 2 buckets of sizes 2^j , $j = \log_2 N$, ..., 1
- This means that there are $O(\log N)$ buckets overall
- $O(\log N)$ buckets of $O(\log N)$ bits: $O(\log^2 N)$ space overall



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Bit stream divided into buckets following DGIM rules

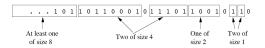
From mmds.org

Answering Queries

- Let $1 \le k \le N$: how many 1's are among the last *k* bits?
- ► Answer:
 - Find leftmost (= with earliest timestamp) bucket b containing some of last k bits
 - *Estimate:* Sum of sizes of buckets right of *b* plus half the size of *b*



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Bit stream divided into buckets following DGIM rules

From mmds.org

Example

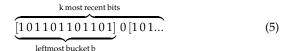
- ► Let *k* = 10: how many 1's are among 0110010110?
- ► Let *t* be timestamp of rightmost bit
- Buckets of timestamps t 1, t 2 and size 1 fully included in k righmost bits
- Bucket of size 2 with timestamp t 4 is also included
- Bucket of size 4 with timestamp t 8 is only partially included
- Estimate: $1 + 1 + 2 + (1/2 \times 4) = 6$, one more than true count

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DGIM: Error of Estimate

Case 1: estimate is less than c

- Let *c* be true count; let leftmost bucket *b* be of size 2^{j}
- ▶ *Worst case:* all 1's in *b* are among *k* most recent bits
- ► Worst case example:



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- Left timestamp of leftmost bucket is t k + 1
- All ones of left most bucket (here: 8) belong to true count
- Estimate counts only half of them (here: 4)

• Because $c \ge 2^j$, error is at most half of c:

$$\frac{\text{estimate}}{\text{true count}} = \frac{c - 2^{j-1}}{c} = 1 - \frac{2^{j-1}}{c} \stackrel{c>2^j}{\ge} 1 - \frac{2^{j-1}}{2^j} = \frac{1}{2}$$
(6)



DGIM: ERROR OF ESTIMATE

Case 2: estimate is larger than c

- Let c be true count; let leftmost bucket b be of size 2^j
- ▶ *Worst case:* only rightmost bit of *b* is among *k* most recent bits, and
- ▶ There is only one bucket for each of sizes 2^{j-1}, ..., 1
- ► Worst case example:

$$\begin{bmatrix} 10110110110\\ \hline 1 \end{bmatrix} 0 \begin{bmatrix} 101011\\ \hline 0 \end{bmatrix} 0 \begin{bmatrix} 10001\\ \hline 0 \end{bmatrix} 0 \begin{bmatrix} 1\\ \hline 0 \end{bmatrix} 0 \begin{bmatrix} 1\\ \hline 0 \end{bmatrix}$$

k most recent bits only one bucket of each size

- Timestamp of leftmost bucket is t k + 1
- Estimate counts half of ones (here: 4); true count is 1
- That yields $c = 1 + 2^{j-1} + \dots + 1 = 1 + 2^j 1 = 2^j$
- Estimate is $2^{j-1} + 2^{j-1} + \dots + 1 = 2^{j-1} + 2^j 1$, so
- Error $\frac{2^{j-1}+2^j-1}{2^j}$ is no greater than 50% of true count

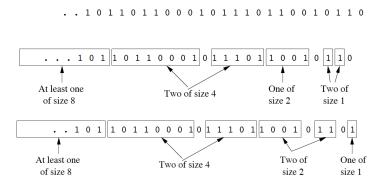
(7)

MAINTAINING DGIM RULES

Upon a new bit with timestamp *t* having arrived:

- Check timestamp *s* of leftmost bucket *b*:
 - if $s \le t N$, drop *b* from list of buckets
- ► If the new bit is 0, do nothing
- ▶ If the new bit is 1, do
 - Create new bucket with timestamp t and size 1
 - On increasing size, while there are three buckets of the same size, do
 - keep the rightmost bucket of that size as is
 - join the two left buckets into one of double the size
 - where the timestamp is that of the rightmost bit
 - For example: joining the two left of the three buckets of size 1 into a bucket of size 2 may create a third bucket of size 2, and so on
- ► *Runtime:* Need to look at $O(\log N)$ buckets, joining is constant time, so processing new bit requires $O(\log N)$ time overall





Buckets following DGIM rules (top), with new 1 arriving (bottom)

From mmds.org



DGIM Algorithm: Reducing the Error

- For some r > 2, allow either r or r 1 buckets of the same size
- Allow this for all but size 1 and largest size, whose numbers may be any of 1, ..., r
- Compute estimate as before
- Extend maintaining the DGIM Bucket Rules in the obvious way
- *Recall:* largest error ^{2^{j-1}+2^j-1}/_{2^j} was made when only one 1 from leftmost bucket *b* was within window



DGIM Algorithm: Reducing the Error

- *Recall:* largest error ^{2j-1+2j-1}/_{2j} was made when only one 1 from leftmost bucket *b* was within window
- ► New error:
 - True count is at most $1 + (r 1)(2^{j-1} + ... + 1) = 1 + (r 1)(2^j 1)$
 - Estimate is $2^{j-1} + (r-1)(2^j 1)$, difference between estimate and true count is $2^{j-1} 1$, so fractional error is

$$\frac{2^{j-1}-1}{1+(r-1)(2^j-1)}$$

which is upper bounded by 1/2(r-1)

• Picking large *r* can limit error to any $\epsilon > 0$



DGIM Algorithm: Extensions

- DGIM can be extended to integers instead of bits
- ► Question is to estimate the sum of last k ≤ N integers from a window of N integers overall
- However, DGIM cannot be extended to streams containing negative integers
- Consider case of integers in range of 0 to $2^m 1$, represented by *m* bits

• *Example:*
$$m = 3$$
, integers 0 to 7



DGIM Algorithm: Extensions

• Consider case of integers in range of 0 to $2^m - 1$, represented by *m* bits

• *Example:*
$$m = 3$$
, integers 0 to 7

integer stream : 2 4 3 1 6 7 ... (9) bit stream : 010 100 011 001 110 111 ...

► Solution:

- Treat each bit of integers as separate stream
- Example from above:

c_0 :	rightmost bit	0	0	1	1	0	1	
c_1 :	middle bit	1	0	1	0	1	1	 (10)
c_2 :	leftmost bit	0	1	0	0	1	1	



DGIM Algorithm: Extensions

► Solution:

- Treat each bit of integers as separate stream
- ► Example from above:

c_0 :	rightmost bit	0	0	1	1	0	1	
c_1 :	middle bit	1	0	1	0	1	1	 (11)
c_2 :	leftmost bit	0	1	0	0	1	1	

Apply DGIM algorithm to each of *m* streams settimate *c_i* for *i*-th stream
 Overall estimate:

$$\sum_{i=0}^{m-1} c_i 2^i$$

• If error is at most ϵ for all *i*, overall error is also at most ϵ



Most Common Elements Decaying Windows

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- Stream: Movie tickets purchased all over the world
- ► *Goal:* Listing currently most "popular" movies
- ► *Currently popular:*
 - Movie that sold plenty of tickets years ago not to be listed
 - ▶ Movie that sold 2*n* tickets last week, for large *n*, currently popular

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- ▶ Movie that sold *n* tickets in last 10 weeks is even more popular
- How to grasp that idea?



- ► *Stream:* Movie tickets purchased all over the world
- ► *Goal:* Listing currently most "popular" movies
- ► Possible solution:
 - One bit stream for each movie
 - ▶ i-th bit in a movie stream is 1 if i-th ticket was for that movie
 - *Example:* Three movies M_1, M_2, M_3

First ticket to M₂, second and third ticket to M₃, fourth ticket to M₁
▶ Pick window of size N, where N is to reflect tickets to be recent



► Possible solution:

• *Example:* Three movies M_1, M_2, M_3

$M_1:$	0	0	0	1	
M_2 :	1	0	0	0	 (13)
M_3 :	0	1	1	0	

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First ticket to M_2 , second and third ticket to M_3 , fourth ticket to M_1

- Pick window of size N, where N is to reflect tickets to be recent
- Estimate number of ones in each stream
 - E.g. use Datar-Gionis-Indyk-Motwani (DGIM) algorithm
 - Estimates number of tickets sold for each movie
- Rank movies by the estimated counts



► Possible solution, summary:

- One bit stream for each movie
- i-th bit in a movie stream is 1 iff i-th ticket was for that movie
- Count number of ones in each stream...
- ... counts tickets for each movie
- Rank movies by ticket counts
- Works for movies, because there only thousands of movies

► Drawback:

Does not work for items at Amazon or tweets per Twitter-user

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too many items or users



- ► *Stream:* Movie tickets purchased all over the world
- ► *Goal:* Listing currently most "popular" movies
- ► Alternative approach:
 - Do not count ones in fixed-size window
 - ▶ Rather, compute "smooth aggregation" of *all* ones in stream
 - Smooth: use weights to rate stream elements in terms of recentness
 - ► The further back in the stream, the less weight given
 - *Example: a_t* most recent stream element

Stream :
$$a_1 \quad a_2 \quad \cdots \quad a_{t-1} \quad a_t$$

Weights : $w_1 \quad w_2 \quad \cdots \quad w_{t-1} \quad w_t$ (14)

where

$$w_1 \le w_2 \le \dots \le w_{t-1} \le w_t$$



EXPONENTIALLY DECAYING WINDOW: DEFINITION

DEFINITION [EXPONENTIALLY DECAYING WINDOW]:

- Let $a_1, a_2, ..., a_t$ be a stream, with a_t most recent element
- Let *c* be small constant, e.g. $c \in [10^{-9}, 10^{-6}]$

The exponentially decaying window for the stream is defined to be

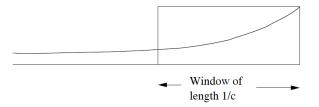
$$\sum_{i=0}^{t-1} a_{t-i} (1-c)^i \tag{15}$$

Weight is $(1 - c)^i$, it holds

$$(1-c)^0 \ge (1-c) \ge (1-c)^2 \ge (1-c)^3 \ge \dots \ge (1-c)^{t-1}$$



EXPONENTIALLY DECAYING WINDOW: DEFINITION



Decaying window and fixed-length window of equal weight \$\$Form <code>mmds.org</code>

- Decaying window puts weight $(1 c)^i$ on (t i)-th element
- ► A window of length 1/*c* puts equal weight 1 on the first 1/*c* elements
- ▶ Both principles distribute the same weight to stream elements overall



UPDATING EXPONENTIALLY DECAYING WINDOWS

Upon arrival of a new element a_{t+1} , one updates the exponentially decaying window $\sum_{i=0}^{t-1} a_{t-i}(1-c)^i$ by

1. multiplying the current window by (1 - c), yielding

$$\sum_{i=0}^{t-1} a_{t-i} (1-c)^{i+1}$$

2. adding a_{t+1} , yielding

$$\sum_{i=0}^{t-1} a_{t-i}(1-c)^{i+1} + a_{t+1} = \sum_{i=0}^{(t+1)-1} a_{(t+1)-i}(1-c)^i$$



EXPONENTIALLY DECAYING WINDOWS: FINDING MOST POPULAR MOVIES

- ► Most Popular Movies: Idea
 - Have a bit stream for each movie, as before
 - Use e.g. $c = 10^{-9}$ (\approx sliding window of size $1/c = 10^{9}$)
 - On incoming movie ticket sale, update all decaying windows, as described above
 - First, multiply all decaying windows by 1 c
 - Add 1 for stream of the movie of the ticket; if there is no stream for that movie, create one
 - Do nothing (add 0) for all other streams
 - ► If any decaying window drops below threshold of 1/2, drop window
 - ▶ Because the sum of all scores is 1/*c*, there cannot be more than 2/*c* movies with score of 1/2 or more
 - ▶ So, 2/*c* is limit on number of movies being tracked at any time
 - In practice, there should be much less movies counted
- *Therefore,* one can apply the technique also for Amazon items and Twitter-users



MATERIALS / OUTLOOK

- ► See Mining of Massive Datasets, chapter 4.6, 4.7
- As usual, see http://www.mmds.org/ in general for further resources
- ► Next lecture: "Mining Data Streams III / Social Networks I"
 - ▶ See Mining of Massive Datasets 4.5; 10.1, 10.2, 10.3

