Lecture 11 Frequent Itemsets II

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TODAY

Overview: Frequent Itemsets II

- Mining Frequent Itemsets: Recap
- ► The Algorithm of Park, Chen and Yu (PCY)
- ► The Multistage Algorithm
- ► The Multihash Algorithm
- ► Toivonen's Algorithm

Learning Goals: Understand these topics and get familiarized



Mining Frequent Itemsets Recap

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FREQUENT ITEMSETS: OVERVIEW

Foundations

- There are *items* available in the market
- ► There are *baskets*, sets of items having been purchased together
- A *frequent itemset* is a set of items that is found to commonly appear in many baskets
- ► The *frequent-itemset problem* is to identify frequent itemsets



FREQUENT ITEMSETS: DEFINITION

DEFINITION [FREQUENT ITEMSET]:

- Let s > 0 be a support threshold
- ► Let *I* be a set of items
- supp(I), the *support* of I, is the number of baskets in which I appears as a subset

An itemset *I* is referred to as *frequent* if

$$\operatorname{supp}(I) \ge s$$
 (1)

that is, if the support of *I* is at least the support threshold



A Priori Algorithm Recap

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A-PRIORI ALGORITHM: CANDIDATE GENERATION AND FILTERING



A-Priori algorithm: Alternating between candidate generation and filtering Adopted from mmds.org

- Construct: C_k itemsets of size k, whose k 1-subsets belong to L_{k-1}
 - ► E.g. C₂ pairs of single items that are members of L₁, so are frequent
- Filter: Members of C_k whose count exceeds s belongs to L_k
- ► *Bottleneck:* Size of *C*₂, the candidate pairs
 - Why? Monotonicity implies in practice(!) that $|C_2| > |C_3| > |C_4| > ...$
 - Although $\binom{n}{2}$ (possible pairs) < $\binom{n}{3}$ (possible triples) < $\binom{n}{4}$...

MONOTONICITY TO THE RESCUE



Itemsets for items A,B,C,D,E Neglecting supersets of infrequent pair {A,B}

Adopted from mmds.org



A-Priori Generating C_2 : Main Memory Usage





Pass 2

Use of main memory during A-Priori passes Pass 1: Generating L_1 ; Pass 2: Generating L_2

Adopted from mmds.org



A-Priori Generating C_2 : Main Memory Usage





Pass 2

Adopted from mmds.org

From *C*³ main memory no longer an issue so naive approaches work, one pass enough



A-Priori Algorithm Extensions The PCY Algorithm

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BOTTLENECK: SIZE OF C_2

- ► The predominant bottleneck in most applications of A-Priori is the size of *C*₂, the candidate pairs
- Several algorithms address to trim down that size
- Exemplary algorithms:
 - ► The algorithm of Park, Chen and Yu (*PCY algorithm*)
 - The Multistage algorithm
 - The Multihash algorithm
- ► We will treat all algorithms in the following



THE PCY ALGORITHM

- Observation: Much of main memory during first pass of A-Priori remains unused
- ► Use that space for a hash table *H* that
 - hashes pairs of items $\{i, j\}$ to
 - ▶ buckets holding integers $H[\{i, j\}] \in \mathbb{N}$, where

 $H[\{i, j\}]$ is number of times any pair hashed to that bucket (2)

- ► To construct *H*, use double loop through baskets:
 - hash each resulting pair to bucket
 - increase the integer in that bucket by one
- A *frequent bucket b* exceeds the support threshold *s*



THE PCY ALGORITHM

- A *frequent bucket b* exceeds the support threshold *s*
- ► So, for any bucket *b*:
 - ▶ If *b* is infrequent, none of the pairs that hashed to *b* are frequent
 - ▶ If *b* is frequent, pairs hashing to it could be frequent
- Definition of candidate set C_2 : For $\{i, j\} \in C_2$, both
 - ► *i* and *j* must be frequent
 - $\{i, j\}$ must hash to a frequent bucket
- ► Use of H in second pass:
 - ► Transform *H* into bitmap *H*′

$$H'[\{i,j\}] = \begin{cases} 1 & \text{if } H[\{i,j\}] \ge s \\ 0 & \text{if } H[\{i,j\}] < s \end{cases}$$



(3)

PCY ALGORITHM: MAIN MEMORY USAGE



Pass 1

Pass 2

Use of main memory during A-Priori passes

Adopted from mmds.org



The Multistage Algorithm



THE MULTISTAGE ALGORITHM

- *Particular Motivation:* Selecting $\{i, j\}$ to be in C_2
- ► In PCY: even when reducing to frequent *i* and *j*, and {*i*, *j*} hashing to frequent buckets, still too many pairs to be counted
- ► So, need to decrease size of *C*² further
- Do this by introducing extra pass:
 - ► *First pass:* as before in PCY
 - Second pass: create another hash table raising a third condition
 - ► *Third pass:* count only pairs that fulfill all three conditions



THE MULTISTAGE ALGORITHM: SECOND PASS

Second pass data structures from PCY:

- ► List *A* on item names to integers
- List C on frequent items: C[i] = k if item i is k-th frequent item, and C[i] = 0 if i-th item is not frequent

• Bitmap $H': H'[\{i, j\}] = 1$ iff $\{i, j\}$ hashed to frequent bucket

• Multistage second pass: consider only $\{i, j\}$, where

- ► (*) both *i* and *j* are frequent
- (**) $H'[\{i, j\}] = 1$, that is $\{i, j\}$ hashes to frequent bucket
- Create H_2 hashing such $\{i, j\}$ to buckets holding integers

 $H_2[\{i,j\}] \in \mathbb{N}$



THE MULTISTAGE ALGORITHM: SECOND PASS

- ► To construct *H*₂, use double loop through baskets:
 - ▶ hash each pair that meets (*) and (**) to bucket, and
 - increase the integer in that bucket by one
- ► Again, a *frequent bucket b* in *H*₂ exceeds the support threshold *s*
- Relative to number of frequent buckets using first *H*, the number of frequent buckets in *H*₂ should be much reduced, because much less pairs are hashed



THE MULTISTAGE ALGORITHM

• Definition of Multistage C_2 : For $\{i, j\} \in C_2$, both

- ► (*) *i* and *j* must be frequent
- (**) $\{i, j\}$ must hash to a frequent bucket according to H
- (***) $\{i, j\}$ must hash to a frequent bucket according to H_2
- Use of C_2 in third pass:

• Keep *A* (items to integers), *C* (frequent items), *H'* (bitmap for *H*)

► Transform *H*² into bitmap *H*″ where

$$H''[b] = \begin{cases} 1 & \text{if } H_2[\{i,j\}] \ge s \\ 0 & \text{if } H_2[\{i,j\}] < s \end{cases}$$
(4)

where *b* is the bucket $\{i, j\}$ hashes to by H_2



THE MULTISTAGE ALGORITHM

- (*Tricky?*) *Question:* Why does (***) not imply (**) and (*)? Weren't all {*i*, *j*} hashed with *H*₂ selected to hash to frequent bucket with *H* and consist of frequent *i* and *j*?
- ► Answer:
 - ► *Yes:* for the second part.
 - But: Any {i, j} that does not consist of frequent i, j, or hash to frequent bucket with H could hash to frequent bucket with H₂ nevertheless, although not having contributed to count in the bucket it hashes to



MULTISTAGE ALGORITHM: MAIN MEMORY USAGE



Pass 1

Pass 2

Pass 3

Use of main memory during Multistage passes

Adopted from mmds.org



The Multihash Algorithm



THE MULTIHASH ALGORITHM

- Particular Motivation: Try to profit from virtues of Multistage algorithm in one, and not two passes
- ▶ So, in *first pass*, use two hash tables *H*₁ and *H*₂,
- ▶ Both *H*¹ and *H*² have only half as many buckets
- ► For proceeding with second pass, turn *H*₁ and *H*₂ into bitmaps *H*′, *H*″ as in Multistage
- Apply exact same conditions as in Multistage for pair {*i*, *j*} to be counted



THE MULTIHASH ALGORITHM

- ▶ Both *H*¹ and *H*² have only half as many buckets
- That is like merging original buckets
- ► Applicability:
 - Majority of buckets infrequent
 - Average bucket size in PCY much lower than threshold s
 - IN Number of frequent buckets limited even when using half as many buckets



THE MULTIHASH ALGORITHM: EXAMPLE

- ► Imagine average bucket count in PCY is *s*/10
- Particular Assumption: Number of pairs of items randomly hashing to frequent bucket is 1/10
- So, with half as many buckets, average count in Multihash is s/5
- Number of pairs of items randomly hashing to frequent buckets with both H₁ and H₂ is 1/25
- So, we deal with approximately 2.5 times less frequent pairs in Multihash than in PCY



MULTIHASH ALGORITHM: MAIN MEMORY USAGE



Pass 1

Pass 2

Use of main memory during Multihash passes

Adopted from mmds.org



Limited-Pass Algorithms

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LIMITED-PASS ALGORITHMS

Strategy

► To save on main memory, consider only a subsample of baskets

► Take into account that one may have

- ► False negatives: itemsets not identified as frequent although they are
- ► *False positives:* itemsets identified as frequent although they are not
- In many applications, a certain amount of false negatives and/or positives is acceptable

Algorithms

- ► *Simple Randomized Algorithm:* basic strategy is briefly discussed
- Savasere, Omiecinski, Navate (SON): not considered in the following
- *Toivonen:* explained here



Simple Randomized Algorithm

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SIMPLE RANDOMIZED ALGORITHM: STRATEGY

- ► Let *m* be the overall number of baskets
- ► *Situation:* main memory can deal with only *k* baskets
- Select probability p such that pm = k
- Run through basket file, and select each basket to be part of sample with probability p
- ▶ If *s* is original support threshold, set *s*′ := *sp* for sample
- Run any A-Priori type algorithm on resulting subset of baskets using s' as support threshold
- ► Declare itemsets frequent in subsample as frequent overall



SIMPLE RANDOMIZED ALGORITHM: ERRORS

- ► *False positive:* Itemset frequent in sample, but not in whole
- ► *False negative:* Itemset frequent in whole, but not in sample
- Eliminating false positives: Evaluate each itemset found to be frequent in sample by running through whole dataset
- ► *Eliminating false negatives:* Cannot eliminate false negatives entirely, but reduce them by choosing *s*' < *sp*, e.g. *s*' = 0.9*sp*



Toivonen's Algorithm

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TOIVONEN'S ALGORITHM I

Algorithm

- Run simple sample strategy at s' = 0.9ps or s' = 0.8ps
- Construct all frequent itemsets from sampled baskets for support threshold s'
- ► Subsequently, construct *negative border* of itemsets in sample

DEFINITION [NEGATIVE BORDER]: An itemset *I* is in the *negative border* iff

- (i) *I* is not frequent, so supp(*I*) < s'
- (ii) All $I' \subset I$ with |I'| = |I| 1 are frequent, so supp $(I') \ge s'$



NEGATIVE BORDER

DEFINITION [NEGATIVE BORDER]: An itemset *I* is in the *negative border* iff

- *I* is not frequent, so supp(I) < s'
- ▶ All $I' \subset I$ with |I'| = |I| 1 are frequent, so supp $(I') \ge s'$



Negative Border: Illustration

From https://who.rocq.inria.fr/Vassilis.Christophides/Big/index.htm



NEGATIVE BORDER: EXAMPLE

- Consider items $\{A, B, C, D, E\}$
- Itemsets found to be frequent: $\{A\}, \{B\}, \{C\}, \{D\}, \{B, C\}, \{C, D\}$
- ► For formal reasons also the empty set Ø is frequent
- ► Negative border:
 - ► {*E*} not frequent, but \emptyset is frequent $\mathbb{I} = |\{E\}| 1$ and \emptyset only subset of {*E*} qualifying for (ii) from definition two slides before
 - ► {*A*, *B*}, {*A*, *C*}, {*A*, *D*}, {*B*, *D*}: not frequent, but singletons contained in them, {*A*}, {*B*}, {*C*}, {*D*}, are
 - ▶ No triples in negative border (e.g. {*B*,*D*} in {*B*,*C*,*D*} not frequent)



TOIVONEN'S ALGORITHM II

- Pass through full dataset: Count all itemsets, found to be frequent or in the negative border in the sample, in the whole
- ► Two possible outcomes:
 - 1. No member of negative border is frequent in whole dataset: frequent itemsets are frequent in sample and in whole
 - Some member of negative border is frequent in whole dataset: there could be even larger sets frequent in the whole
 no guarantees, repeat the algorithm



TOIVONEN'S ALGORITHM: PROOF

► *Eliminating false positives:* As usual for simple randomized algorithms, by raising counts in the whole dataset, one can filter out itemsets that are frequent in the sample, but not in the whole dataset ✓

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- No false negatives: If no member of the negative border is frequent in the whole dataset, show there is no itemset that
 - ► is frequent in the whole
 - while, in the sample not among the frequent itemsets



TOIVONEN'S ALGORITHM: PROOF

- ► *Proof of no false negatives:* Suppose the contrary: there is *S*
 - that is frequent in the whole
 - but not frequent in the sample
- ▶ By monotonicity, all subsets of *S* are frequent in the whole
- Choose $T \subseteq S$ of the *smallest* possible size such that still T is not frequent in the sample



Negative Border: Illustration

From https://who.rocq.inria.fr/Vassilis.Christophides/Big/index.htm

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TOIVONEN'S ALGORITHM: PROOF

- *Claim: T* is in the negative border of the sample
- ► Proof of Claim:
 - ► All proper subsets of *T* are frequent in the sample, because *T* was chosen of the smallest possible size
 - ► *T* itself is not frequent in the sample
- We obtain that *T* was in the negative border of the sample, but frequent in the whole, which is a contradiction!



MATERIALS / OUTLOOK

- ► See Mining of Massive Datasets, sections 6.1–6.4
- As usual, see http://www.mmds.org/ in general for further resources
- ► Next lecture: 'Recommendation Systems"
 - ► See Mining of Massive Datasets, 9.1, 9.3, 9.4

