# Learning in Big Data Analytics Support Vector Machines 

Alexander Schönhuth

Bielefeld University
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## Perceptrons Revisited

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- A perceptron divides the space into two half spaces
- Half spaces capture the two different classes
- Normal vector alternative description of half space


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- Several half spaces (normal vectors) divide training data
- Question: any half space optimal, in a sensibly defined way?
- What to do if data cannot be separated (is non-separable)?


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## Support Vector Machines: Motivation

- Support vector machines (SVM's) address to choose most reasonable half space
- SVM's choose half space that maximizes the margin, i.e. the distance between data points and half space
- If separable, maximize distance between hyperplane and closest data points
- If not separable, minimize loss function that


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- If separable, maximize distance between hyperplane and closest data points
- If not separable, minimize loss function that
- penalizes misclassified points
- penalizes points correctly classified but too close to hyperplane (to a lesser extent)


## Perceptron Revisited



- Outer hyperplanes come very close to data points
- So, inner hyperplanes are likely the better choice
- Try to make explicit!


## Separable Data

## Separable Data



- Goal: Select hyperplane $\mathbf{w} \cdot \mathbf{x}+b=0$ that maximizes distance $\gamma$
- Intuition: The further away data from hyperplane, the more certain their classification
- Increases chances to correctly classify unseen data (to generalize)


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## Support Vectors



- Two parallel hyperplanes at distance $\gamma$ touch one or more of support vectors
$\Rightarrow$ In most cases, $d$-dimensional data set has $d+1$ support vectors (but there can be more)


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## Problem Formulation: First Try

Let $\left(\mathbf{x}_{1}, y_{1}\right), \ldots,\left(\mathbf{x}_{n}, y_{n}\right)$ be a training data set, where $\mathbf{x}_{i} \in \mathbb{R}^{d}, y_{i} \in\{-1,+1\}, i=1, \ldots, n$.

Problem: By varying $\mathbf{w}, b$, maximize $\gamma$ such that

$$
\begin{equation*}
y_{i}\left(\mathbf{w} \mathbf{x}_{i}+b\right) \geq \gamma \quad \text { for all } i=1, \ldots, n \tag{1}
\end{equation*}
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Issue

- Replacing $\mathbf{w}$ and $b$ by $2 \mathbf{w}$ and $2 b$ yields $y_{i}\left(2 \mathbf{w} \mathbf{x}_{i}+2 b\right) \geq 2 \gamma$
- There is no optimal $\gamma$


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Problem badly formulated Try again!

## Problem Formulation: Solution

- Data set $\left(\mathbf{x}_{i}, y_{i}\right), i=1, \ldots, n$ as before; let $H:=\{\mathbf{x} \mid \mathbf{w} \mathbf{x}+b=0\}$ be the hyperplane given by $\mathbf{w}$ and $b$.

$$
d\left(\mathbf{x}_{i}, H\right):=\min \left\{d\left(\mathbf{x}_{i}, \mathbf{x}\right) \mid \mathbf{w} \mathbf{x}+b=0\right\}
$$

be the distance between $\mathbf{x}_{i}$ and $H$.

- Solution: Impose additional constraint: consider only combinations $\mathrm{w} \in \mathbb{R}^{d}, b \in \mathbb{R}$ such that for support vectors x
- Good Formulation: By varying $\mathbf{w}, b$, maximize $\gamma$ such that

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y_{i}(w x+b) \in\{-1,+1\}
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\begin{equation*}
d\left(\mathbf{x}_{i}, H\right) \geq \gamma \quad \text { for all } i=1, \ldots, n \tag{4}
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and (3) applies

## Alternative Problem Formulation I



- $\mathbf{w}, b, \gamma$ determined according to (3),(4)
$\rightarrow x_{2}$ is support vector on lower hyperplane, so by (3), $w x_{2}+b=-1$
$\rightarrow$ Let $\mathbf{x}_{1}$ be the projection of $\mathbf{x}_{2}$ onto upper hyperplane:

$$
\begin{equation*}
x_{1}=x_{2}+2 \gamma \frac{\mathbf{w}}{\|w\|} \tag{5}
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## Alternative Problem Formulation II

That is, further, $\mathbf{x}_{1}$ is on the hyperplane defined by $\mathbf{w} \mathbf{x}+b=1$, meaning

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Substituting $\mathbf{x}_{1}=\mathbf{x}_{2}+2 \gamma \frac{\mathbf{w}}{\|\mathbf{w}\|}$ (5) into (6) yields

$$
\begin{equation*}
\mathbf{w} \cdot\left(\mathbf{x}_{2}+2 \gamma \frac{\mathbf{w}}{\|\mathbf{w}\|}\right)+b=1 \tag{7}
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\mathbf{w} \mathbf{x}_{2}+b+2 \gamma \frac{\mathbf{w w}}{\|\mathbf{w}\|}=1 \tag{8}
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Because $\mathbf{w w}=\|\mathbf{w}\|^{2}$, and by further regrouping, we conclude that

$$
\begin{equation*}
\gamma=\frac{1}{\|\mathbf{w}\|} \tag{9}
\end{equation*}
$$

## Alternative Problem Formulation III

Let dataset $\left(\mathbf{x}_{i}, y_{i}\right), i=1, \ldots, n$ be as before.
EqUiValent Problem Formulation:
By varying $\mathbf{w}, b$, minimize $\|\mathbf{w}\|$ subject to

$$
\begin{equation*}
y_{i}\left(\mathbf{w} \mathbf{x}_{i}+b\right) \geq 1 \quad \text { for all } i=1, \ldots, n \tag{10}
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$$

## Alternative Problem Formulation III

Let dataset $\left(\mathbf{x}_{i}, y_{i}\right), i=1, \ldots, n$ be as before.
EQuivalent Problem Formulation:
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$$

Optimizing under Constraints

- Topic is broadly covered
- Many packages can be used
- Target function $(\|\mathbf{w}\|)^{2}=\sum_{i} w_{i}^{2}$ quadratic; well manageable


## Example

## Non Separable Data

## Non Separable Data Sets



Situation:

- Some points misclassified, some too close to boundary bad points
- Non separable data: any choice of $\mathbf{w}, b$ yields bad points


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## Non Separable Data: Motivation



- Situation: No hyperplane can separate the data points correctly
- Approach:


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- Determine appropriate penalties for bad points
- Solve original problem, by involving penalties


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## Non Separable Data: Motivation II

Let $\left(\mathbf{x}_{i}, y_{i}\right), i=1, \ldots n$ be training data, where

- $\mathbf{x}_{i}=\left(x_{i 1}, \ldots, x_{i d}\right)$,
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and let $\mathbf{w}=\left(w_{1}, \ldots, w_{d}\right)$.
Minimize the following function:

$$
\begin{equation*}
f(\mathbf{w}, b)=\frac{1}{2} \sum_{j=1}^{d} w_{j}^{2}+C \sum_{i=1}^{n} \max \left\{0,1-y_{i}\left(\sum_{j=1}^{d} w_{j} x_{i j}+b\right)\right\} \tag{11}
\end{equation*}
$$

## Non Separable Data: Motivation II

$$
f(\mathbf{w}, b)=\underbrace{\frac{1}{2} \sum_{j=1}^{d} w_{j}^{2}}_{\text {Seek minimal }\|\mathbf{w}\|}+\underbrace{C \sum_{i=1}^{n} \max \left\{0,1-y_{i}\left(\sum_{j=1}^{d} w_{j} x_{i j}+b\right)\right\}}_{\text {Bad point penalty }}
$$

$\rightarrow$ Minimizing $||w||$ equivalent to minimizing monotone function of $||w|$ ne Minimizing $f$ seeks minimal $\|\mathbf{w}\|$

- Vectors w and training data balaneed in terms of basic units:

- $C$ is a regularization parameter


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\frac{\partial\left(\|\mathbf{w}\|^{2} / 2\right)}{\partial w_{i}}=w_{i} \quad \text { and } \quad \frac{\partial\left(\sum_{j=1}^{d} w_{j} x_{i j}+b\right)}{\partial w_{i}}=x_{i j}
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- $C$ is a regularization parameter
- Large C: minimize misclassified points, but accept narrow margin
- Small C: accept misclassified points, but widen margin


## Non Separable Data: Hinge Function

Let the hinge function $L$ be defined by

$$
\begin{equation*}
L\left(\mathbf{x}_{i}, y_{i}\right)=\max \left\{0,1-y_{i}\left(\sum_{j=1}^{d} w_{j} x_{i j}+b\right)\right\} \tag{12}
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$\rightarrow L\left(\mathbf{x}_{i}, y_{i}\right)=0$ iff $\mathbf{x}_{i}$ on the correct side of hyperplane with sufficient margin

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- $L\left(\mathbf{x}_{i}, y_{i}\right)=0$ iff $\mathbf{x}_{i}$ on the correct side of hyperplane with sufficient margin
- The worse $\mathbf{x}_{i}$ is located the greater $L\left(\mathbf{x}_{i}, y_{i}\right)$


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Partial derivatives of hinge function:

$$
\frac{\partial L}{\partial w_{j}}= \begin{cases}0 & \text { if } y_{i}\left(\sum_{j=1}^{d} w_{j} x_{i j}+b\right) \geq 1  \tag{13}\\ -y_{i} x_{i j} & \text { otherwise }\end{cases}
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Reflecting:

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## General / Further Reading

Literature

- Mining Massive Datasets, Chapter 12, Section 3: http: / / infolab.stanford.edu/~ullman/mmds/ch12.pdf


## Thank you for listening!

